MHS2014

2014 International Symposium on Micro-NanoMechatronics and Human Science (From Micro & Nano Scale Systems to Robotics & Mechatronics Systems) Symposium on "Hyper Bio Assembler for 3D Cellular System Innovation" Grant-in-Aid for Scientific Research on Innovative Areas, MEXT, Japan Nov. 9 - 12, 2014, Nagoya, Japan

November 9 (Sun)

Location: Noyori Conference Hall

23nd International Micro Robot Maze Contest 2014

Categories:

Category 0:	Micro Robot Racer
Category 1:	Teleoperated Micro Robot Maze Competition
Category 2a:	Fully Autonomous Micro Robot Maze Competition
Category 2b:	Remote-Controlled Micro Robot Maze Competition
Category 3a:	Biped Micro Robot Competition
Category 3b:	Multiple Legged Micro Robot Competition

Category 4: Micro Robot Performance

Time Schedule:

16:00 Break

16:30 Award Ceremony and Closing

09:30	Opening Ceremony
09:45	Category 0: Micro Robot Racer
11:30	Category2a: Fully Autonomous Micro Robot Maze Competition
12:00	Category3a: Biped Micro Robot Competition
12:20	Lunch Break
13:00	Category4: Micro Robot Performance
13:15	Category 1: Teleoperated Micro Robot Maze Competition
14:15	Category2b: Remote-Controlled Micro Robot Maze Competition
15:25	Category3b: Multiple Legged Micro Robot Competition

November 10 (Mon) Location: Noyori Conference Hall

Opening Remarks Conference Room 1

Chairperson: Fumihito Arai, Nagoya University

09:00-9:20 Prof. Toshio Fukuda, Meijo University, Nagoya University, Japan,

Beijing Institute of Technology, China Prof. Tatsuo Arai, Osaka University, Japan

Plenary Talk Conference Room 1

Chairperson: Prof. Takehisa Matsuda, Professor Emeritus, Kyushu University

09:20-10:10 Plenary Talk 1

Regenerative Medicine from the Viewpoint of Materials Science

- Regenerative Research and Therapy -

Prof. Yasuhiko Tabata, Department of Biomaterials, Institute for Frontier

Medical Sciences, Kyoto University, Japan

10:10-10:20 *Coffee Break*

Chairperson: Makoto Nakamura, Toyama University

10:20-11:10 Plenary Talk 2

Bio - 3D Printing: Challenges and Opportunities

Prof. Wei Sun, Albert Soffa Chair Professor; Drexel University, USA 1000plan Chair Professor and Director, Biomanufacturing Engineering

Research Institute, Tsinghua University, Beijing, China

Chairperson: Yasuhisa Hasegawa, Nagoya University

11:10-12:00 Plenary Talk 3

Biologically Inspired Approach Towards Implementation of Bionic Arm *Prof. Sang-Rok Oh, Korea Institute of Science and Technology, Korea*

12:00-12:50 *Lunch*

Poster Area(1st floor)

Poster session I

Chairperson: Masahiro Ohka, Nagoya University

Seiichi Hata, Nagoya University Norikazu Suzuki, Nagoya University

12:50-14:20

- MP-1 Development and Evaluation of a Wheelchair Lifter for Automobile Use Kazuto Miyawaki and Toshimi Sato, Akita National College of Technology, Japan
- MP-2 Task Descriptions and a Program Execution for Framework for an Autonomous Robot

 Yoshitatsu Suzuki, Kengo Emoto, Ryota Kato, Ryoji Tanaka, Eiichiro Tani, Hidekazu, Yamada and Kyoichi Tstuno, Meijo University, Japan
- MP-3 Work Environments Construction for an Autonomous Robot

 Kengo Emoto, Yoshitatsu Suzuki, Ryota Kato, Ryoji Tanaka, Hidekazu Yamada,

 Eiichiro Tani and Kyoichi Tatsuno, Meijo University, Japan
- MP-4 Navigation Control for an Exploration Rover with Microwave Doppler Sensors (Fabrication of Third Prototype Rover and Experiments)

 Masahiro Isogai Yasuhiko Nawa and Toru Iijima, Aichi University of Technology, Japan
- MP-5 Estimation of Vibration Stimulus Threshold for Inducing Kinesthetic Illusion Masakazu Honda, Hiroyuki Karakawa, Koichi Akahori, Tetsu Miyaoka and Masahiro Ohka, Industrial Research Institute of Shizuoka Prefecture, Japan
- MP-6 Auto-selection of Optimal Visual Representation for a Flying Robot based on Altitude Control

 Shohei Suzuki and Kosuke Sekiyama, Nagoya University, Japan
- MP-7 Design Concept of a New Bio-inspired Tactile Sensor Based on Main Pulvinus Motor Organ Cells Distribution of Mimosa Pudica Plant
 Siti Nora Basir, Hanafiah Yussof, Nur Ismarrubie Zahari and Fahrulrodzi Idris,
 Universiti Teknologi MARA, Malaysia
- MP-8 Influence of Target-target Distance for Composition Distribution in New Facing Targets Sputtering

 Takuya Maetani, Yutaka Nakamitsu, Junpei Sakurai and Seiichi Hata,

 Nagoya University, Japan

- MP-9 Observation of the Permeation on the Subcutaneous during the Administration of Drug and Development of a Needle

 Kento Kawata, Kazuyoshi Tsuchiya, Kagemasa Kajiwara and Minoru Kimura,

 Nagoya University, Japan
- MP-10 Selection of the Best Shape for A Micro Painless Needle

 Hideaki Kimoto, Takehiko Inoue, Kazuyoshi Tsuchiya, Kagemasa Kajiwara,

 Minoru Kimura, Tokai University, Japan
- MP-11 One Double-stranded DNA Probes as Classifier of Multi Targeting Strand Wibowo Adi and Kosuke Sekiyama, Nagoya University, Japan
- MP-12 Levitation Energy of Piezoelectric Actuator using a Levitation Mechanism Shori Sone, Akihiro Torii, Kae Doki and Suguru Mototani, Aichi Institute of Technology, Japan
- MP-13 A DC Voltage Estimation at the Maximum Power Point of a Series Parallel Connection PV System with Partial Shade

 Jun Ishikawa, Atsushi Nakata, Akihiro Torii, Kae Doki and Suguru Mototani,

 Aichi Institute of Technology, Japan
- MP-14 Multi Geometrical Image Processing Based on Active Vision Agent
 Sukarnur Che Abdullah, Masahiro Ohka, Jamaluddin Mahmud,
 M. Azzeim M., Jusoh and Juri Saedon, Universiti Teknologi MARA, Malaysia
- MP-15 Single Particle Tracking Study on Diffusion Process in a Polymer Matrix Yu Matsuda, Ryo Iwao, Hiroki Yamaguchi, and Tomohide Niimi, Nagoya University, Japan
- MP-16 Robust Packaging of QCR Load Sensor for Biosignal Detection Yuichi Murozaki, Shinya Sakuma and Fumihito Arai, Nagoya University, Japan
- MP-17 Shape Optimization of Neck Myoelectric Signal Control-type Speaking Valve Katsutoshi Oe and Kohei Sakurai, Daiichi Institute of Technology, Japan
- MP-18 Open Microfluidic Chip using Air-liquid Interface for Single Cell Isolation and Aspiration
 Song Woneui, Taisuke Masuda, Hayao Nakanishi and Fumihito Arai, Nagoya University, Japan
- MP-19 Optically Controllable Muscle for Cell-based Microdevice

 Toshifumi Asano, Toru Ishizuka, Hiromu Yawo and Keisuke Morishima,
 Osaka University, Japan

- MP-20 Fall Detection for Elderly by using an Intelligent Cane Robot based on Center of Pressure (COP) Stability Theory
 Pei Di, Jian Huang, Shotaro Nakagawa, Kosuke Sekiyama and Toshio Fukuda, Nagoya University, Japan
- MP-21 Understanding of Human Tactile Mechanism in comparing Material Properties through the Analysis of Displacement on Foil Surface

 Mohammad Azzeim Mat Jusoh, Masahiro Ohka, Yu Chun Wang and Tetsu Miyaoka, Nagoya University, Japan

14:20-14:25 *Coffee Break*

Silver Jubilee Special Talk

Conference Room 1

Chairperson: Osamu Suzuki, Tohoku University

14:25-14:55 Silver Jubilee Special Talk

Engineered Biointerfaces for the Control of Cell Adhesion and

Bioanalytical Devices

Prof. Jürgen Rühe, Laboratory for Chemistry and Physics of Interfaces,

Department of Microsystems Engineering (IMTEK),

University of Freiburg, Germany

Session MP1-1: (Organized Session): Functional Interfaces in Micro-nanofluidics Conference Room 1

	Conference Room 1
Chairperson:	Yoko Yamanishi, Shibaura Institute of Technology Shingo Nakamura, Shibaura Institute of Technology
15:05-15:20	Development of a Lightweight Manipulator with Constraint Mechanism Daichi Matsuoka, Guillermo Enriquez, Huei Ee Yap and Shuji Hashimoto, Waseda University, Japan
15:20-15:35	Design of Electrostatic Adhesion Device using the Flexible Electrodes Akifumi Takada, Shingo Nakamura, Yoko Yamanishi, Shinji Hashimura, Sumito Nagasawa, Takanobu Kogure and Shingo Maeda, Shibaura Institute of Technology, Japan
15:35-15:50	On-chip Force Measurement System for Investigating Plant-root Growth Hirotaka Hida, Katsuya Ozoe, Isaku Kanno, Tetsuya Higashiyama and Michitaka Notaguchi, Kobe University, Japan
15:50-16:05	Minimally-invasive Local Injection by Electrically-driven Narrow Orifice Channel Kazuki Takahashi, Shun Omi and Yoko Yamanishi, Shibaura Institute of Technology, Japan
16:05-16:20	Experimental Study on Dielectric Properties of Yeast Cells in Micro Channel by Impedance Spectroscopy Jiafeng Yao, Tatsuya Kodera, Achyut Sapkota, Hiromichi Obara and Masahiro Takei, Chiba University, Japan
16:20-16:35	A Simple Ion Concentration Measurement System using a Microfluidic Device with ISFET Sensors Tsuyoshi Miura and Akira Yamada, Aichi Institute of Technology, Japan

Session MP2-1: (Organized Session): Robot System Control and Its Software Conference Room 2

Chairperson:	Kenichi Ohara, Meijo University Tomohito Takubo, Osaka City University
15:05-15:20	Precise Time Synchronization Device for Distributed Robot System Cooperation Kenichi Ohara, Meijo University, Japan
15:20-15:35	3D Movement of Legged Robot in Narrow Space Takeshi Toda, Kenichi Ohara, Kazuto Kamiyama, Masaru Kojima, Mitsuhiro Horade, Yasushi Mae and Tatsuo Arai, Osaka University, Japan
15:35-15:50	Development of Simplified Haptic Interface for Two-finger Micro-manipulator Kazuto Kamiyama, Masaru Kojima, Mitsuhiro Horade, Yasushi Mae and Tatsuo ARAI, Osaka University, Japan
15:50-16:05	3D Gait Planning Based on Discrete-time Kinematic Model of Biped Walking Daiki Kobayashi, Tomohito Takubo and Atsushi Ueno, Osaka City University, Japan
16:05-16:20	Camera View Centered Mobile Robot Control Interface Naoto Hirakawa, Tomohito Takubo and Atsushi Ueno, Osaka City University, Japan
16:35-16:45	Coffee Break

Session MP1-2: (Organized Session): Young Researchers in Biomedical Engineering Conference Room 1

Chairperson: Taisuke Masuda, Nagoya University Kazuyoshi Tsuchiya, Tokai University 16:45-17:00 Evaluation of Enzyme Immobilization Methods on Microglucose Sensors Integrated to a Microfluidic Device Ryo Yazaki, Sho Shimasaki, KazuyoshiTsuchiya, Teruo Fujii and Hiroshi Kimura, Tokai University, Japan 17:00-17:15 Pinpoint Chemical Stimulation at a Single-cell Scale by Microfluidic **Technology** Masayuki Horayama, Tomoki Ohkubo, Kenta Arai, Kazuya Kabayama, Teruo Fujii and Hiroshi Kimura, Tokai University, Japan 17:15-17:30 Single-cell Picking by Integrated Micropipette having Sensor for Passage Detection of Cell Kazuya Tashiro, Taisuke Masuda and Fumihito Arai, Nagoya University, Japan 17:30-17:45 Comparison and Implementation of Motion Detection Methods for Sperm **Detection and Tracking** A. Nurhadiyatna, A.L. Latifah, D. Fryantoni, T. Wirahman, R. Wijayanti, and F.H. Muttagien Research Center for Informatics, Indonesian Institute of Sciences (LIPI), Indonesia A Computer Simulation of Reconstitute Systems of Motor Proteins 17:45-18:00 Revealed Biophysical Phenomena Relevant to Biomedical Engineering Takahiro Nitta and Yuki Ishigure, Gifu University, Japan

Session MP2-2 Robotics and Mechatronics-1

Chairperson:	Kosuke Sekiyama, Nagoya University Syamimi Shamsuddin, Universiti Teknologi MARA
16:45-17:00	Muscle Biopsy System for Extracting Fibrous Muscular Tissue Akari Ushida and Makoto Nokata, Ritsumeikan University, Japan
17:00-17:15	Light Driven SMA Actuator using Optical Waveguide Made of Past Type Organic Material Keita Usaki, Yuichi Ashida, Takefumi Kanda, Koichi Suzumori and Shuichi Wakimoto, Okayama University, Japan
17:15-17:30	DNA-based Swarm Intelligence Inspired Computation Rizki Mardian and Kosuke Sekiyama, Nagoya University, Japan
17:30-17:45	Humanoid Robot Nao as a Teaching Tool of Emotion Recognition for Children with Autism using the Android App Mohd Azfar Miskam, Syamimi Shamsuddin, Mohd Ridzuan Abdul Samat, Hanafiah Yussof, Husna Ahmad Ainudin and Abdul Rahman Omar, Universiti Teknologi MARA, Malaysia
17:45-18:00	Support of COG Trajectory Tracking by Arm-swing with Bipedal Walking Taisuke Kobayashi, Kosuke Sekiyama, Tadayoshi Aoyama, Yasuhisa Hasegawa and Toshio Fukuda, Nagoya University, Japan

November 11 (Tue) Location: Noyori Conference Hall

Technical Sessions

Session TA1-1: (Organized Session): Bio-Assembler -1

Chairperson:	Masaru Kojima, Osaka University Masaru Takeuchi, Nagoya University
09:00-09:15	Microassembly of Spheroids by Thermoresponsive Gel Probe Masaru Takeuchi, Masahiro Nakajima, Toshio Fukuda and Yasuhisa Hasegawa, Nagoya University, Japan
09:15-09:30	Assembly of the Hybrid Multicellular Spheroids using Epithelial Cells and Hydrogel Beads Wakako Motoyama, Shigehisa Aoki and Nobuhiko Kojima, Yokohama City University, Japan
09:30-09:45	Circulatory Culture System for Elastic Fiber Development of Tissue-engineered Blood Vessels Yuka Yamagishi, Taisuke Masuda, Mitsuhiro Ukiki, Michiya Matsusaki, Mitsuru Akashi, Utako Yokoyama and Fumihito Arai, Nagoya University, Japan
09:45-10:00	Chick Embryo Cultured in a Cubic Eggshell as a Promising Animal Model Wenjing Huang, Fumihito Arai, and Tomohiro Kawahara, Kyushu Institute of Technology, Japan
10:00-10:15	Construction of Cell Sheet-based 3D Tissues with Designed Cell Orientation using Anisotropic Cell Sheets Hironobu Takahashi, Tatsuya Shimizu, Masamichi Nakayama, Masayuki Yamato and Teruo Okano, Tokyo Women's Medical University, Japan
10:15-10:30	In Vitro Assessment of Osteoblastic Differentiation of Encapsulated Stromal Cells in Alginate/Octacalcium Phosphate Kosei Endo, Takahisa Anada, Masumi Yamada, Minoru Seki, Keiichi Sasaki and Osamu Suzuki, Tohoku University, Japan

Session TA2-1: (Organized Session): Bio-manipulation and Its Applications Conference Room 2

Chairperson:	Masahiro Nakajima, Nagoya University Tomohiro Kawahara, Kyushu Institute of Technology
09:00-09:15	On-line Tracking and Stimulation of Swimming Microorganism by On-Chip Microrobot Belal Ahmad, Tomohiro Kawahara, Takashi Yasuda and Fumihito Arai, Kyushu Institute of Technology, Japan
09:15-09:30	Directly Measurement of Shear Force of a Single Adhesion Cell using a Self-sensitive Cantilever Shigetaka Hashimoto, Makoto Adachi and Futoshi Iwata, Shizuoka University, Japan
09:30-09:45	High Performance Cell Membrane Perforation System for Cell Suspensions Takaaki Mori, Yukihiro Akiyama, Shogo Unuma and Takashi K. Saito, Akita Prefectural University, Japan
09:45-10:00	Development of a Single Cell Electroporation Method using a Scanning Ion Conductance Microscope with a Theta Type Probe Pipette Satoshi Sakura, Koji Yamazaki, Tatsuo Usiki and Futoshi Iwata, Shizuoka University, Japan
10:00-10:15	On-chip Cell Manipulation by Vibration-induced Whirling Flow Takeshi Hayakawa, Shinya Sakuma and Fumihito Arai, Nagoya University, Japan
10:15-10:30	Surface-tension Microscopy by Noncontact Meniscus-manipulation Nobuyuki Tanaka, Makoto Kondo, Hiroaki Sugiyama, Masayuki Yamato, Teruo Okano and Jun Miyake, Osaka University
10:30-10:40	Coffee Break

Session TA1-2: (Organized Session):Bio-Assembler -2

ConferenceRoom 1

Masumi Yamada, Chiba University Chairperson: Shinji Sugiura, AIST 10:40-10:55 Automated Construction System for Fine Lattice Shape Structures Based on Alginate Gel Fiber Akira Fukushima, Masaru Kojima, Kenichi Ohara, Mitsuhiro Horade, Kazuto Kamiyama, Yasushi Mae and Tatsuo Arai, Osaka University, Japan 10:55-11:10 Shape Control of Cell-embedding Hydrogel Microstructures Utilizing Non-equilibrium Aqueous Two-phase Systems Natsuki Nakaijma, Kenta Yamakoshi, Yuya Yajima, Masumi Yamada and Minoru Seki, Chiba University, Japan 11:10-11:25 Nano-scale Physical Surface Coating of Temperature-responsive Polymers for Cell Sheet Fabrications Masamichi Nakayama, Yurika Kimura, Hideko Kanazawa, Masayuki Yamato and Teruo Okano, Tokyo Women's Medical University, Japan 11:25-11:40 Real-time Local Environmental Stimulation System with Visual Feedback Control Takahiro Motoyoshi, Masaru Kojima, Kenichi Ohara, Mitsuhiro Horade, Kazuto Kamiyama, Yasushi Mae and Tatsuo Arai, Osaka University, Japan 11:40-11:55 Microscale Cell Manipulation by using Photodegradable Hydrogel Shinji Sugiura, Fumiki Yanagawa, Toshiyuki Takagi, Kimio Sumaru, Toshiyuki Kanamori, Masato Tamura and Hirofumi Matsui, AIST, Japan

Session TA2-2: (Organized Session): Community-Centric Robotics

11:55-12:55 *Lunch*

Chairperson:	Janos Botzheim, Tokyo Metropolitan University Naoyuki Kubota, Tokyo Metropolitan University
10:40-10:55	Real-time Sequentially Decision for Optimal Action using Prediction of the State-Action Pair Masashi Sugimoto and Kentarou Kurashige, Muroran Institute of Technology, Japan
10:55-11:10	Development of Remote Controllable Visiting Robot Considering Local Situation Shota Mitsumura, Yoshinobu Akimoto, Eri Sato-Shimokawara and Toru Yamaguchi, Tokyo Metropolitan University, Japan
11:10-11:25	Acquisition of the Human Characteristics through Dialogue with a Robot at Home Tetsuya Kaneko, Reona Gomi, Eri Sato-Shimokawara, and Toru Yamaguchi Tokyo Metropolitan University, Japan
11:25-11:40	Exercise Support System with Robot Partner based on Feeling of Self-efficacy Saika Ono, Junya Kusaka, Takenori Obo and Naoyuki Kubota, Tokyo Metropolitan University, Japan
11:40-11:55	Facial and Gestural Expression Generation for Robot Partners Jinseok Woo, Janos Botzheim and Naoyuki Kubota, Tokyo Metropolitan University, Japan

Poster Area(1st floor)

Poster session II

Chairperson Masahiro Ohka, Nagoya University

Masumi Yamada, Chiba University Osamu Suzuki, Tohoku University

12:55-14:25

TP-01 Two-axis Scanning Micro Mirror Device with Thick Film Metallic Glass Cu-Zr-Ti and Parylene-C
Shigetaka Watanabe, Yutaka Nakamitsu, Sakurai Junpei, Mizue Mizojiri and Seiichi Hata, Nagoya University, Japan

- TP-02 SEM-CT Observation of Bone from Mice using Environmental-SEM
 Masahiro Nakajima, Masaru Takeuchi, Taisuke Masuda, Takahisa Anada,
 Osamu Suzuki, Toshio Fukuda, Qiang Huang and Yasuhisa Hasegawa,
 Nagoya University, Japan
- TP-03 Control of Cell Orientation in Mesenchymal Cell Sheets Fabricated using Microstructured Mesh Sheet
 Rina Yanaru, Kennedy Omondi Okeyo, Osamu Kurosawa, Hidehiro Oana, Hidetoshi Kotera and Masao Washizu, The University of Tokyo, Japan
- TP-04 Catalytic Driven Micro-nanorobots Fabricated by Direct Laser Writing
 Azrena Abu Bakar, Masahiro Nakajima, Masaru Takeuchi and Toshio Fukuda,
 Nagoya University, Japan
- TP-05 Design of CuO Anti-reflection Structure for Thin-film Thermoelectric Generator Tasuku Kondou, Mizue Mizoshiri and Seiichi Hata, Nagoya University, Japan
- TP-06 Evaluation of Hand Direction for Stroke Patient Based on 3R Under-actuated Robot Manipulator

 Mohd Amiruddin Fikri, Sukarnur Che Abdullah and Mohd Adam Tan,

 Universiti Teknologi MARA, Malaysia
- TP-07 On-chip Measurement of Mechanical Properties of a Single Cyanobacteria using Direct-outer-drive Mechanism

 Takayuki Hasegawa, Shinya Sakuma and Fumihito Arai, Nagoya University, Japan
- TP-08 Detection of Influenza Virus Subtype using Quartz Crystal Microbalance Shuichiro Kagiyama, Taisuke Masuda, Kunihiro Kaihatsu, Nobuo Kato and Fumihito Arai, Nagoya University, Japan

- TP-09 Generation of Rotational Flow in Microfluidics Device for Formation of Spheroid Masaru Kojima, Mitsuhiro Horade, Hirochika Takai, Kenichi Ohara, Tamio Tanikawa, Kazuto Kamiyama, Yasushi Mae1 and Tatsuo Arai, Osaka University Japan
- TP-10 Non-contact Measurement of Oxygen Consumption Rate of Single Oocyte using Stripe-shaped Fluorescence Sensor on Microfluidic Chip Masanobu Kito, Hisataka Maruyama and Fumihito Arai, Nagoya University, Japan
- TP-11 MEMS-based Dispenser Array for Selective Immobilization of Molecular Recognition Elements on Bio-image Sensor

 Moeto Nagai, Satoshi Soga, Tokuma Miyamoto, Takahiro Kawashima and Takayuki Shibata, Toyohashi University of Technology, Japan
- TP-12 Quantitative Image Analyses of Nuclear Dynamics in Migrating Neurons
 Hiroki Umeshima, Yuu Kure, Kenichi Nomura, Shuhei Yoshikawa, Shinya Sakuma,
 Fumihito Arai, Makoto Kaneko and Mineko Kengaku, Kyoto University, Japan
- TP-13 Control of Structure of Multi-channel Collagen Gel Beads Kazuya Furusawa, Akimasa Fukui and Naoki Sasaki, Hokkaido University, Japan
- TP-14 Cell Origami for Cell-sheet Engineering
 Fumiaki Tomoike, Yoshikatsu Akiyama, Masayuki Yamato and Shoji Takeuchi,
 Tokyo Women's Medical University, Japan
- TP-15 Fabrication of Retinal Microvessel Model using Three-dimensional Membrane Ippei Kato, Mamoru Mitsuishi, Naohiko Sugita, Kanako Harada, Shinichi Tanaka, Yasuo Noda, Takashi Ueta and Fumihito Arai, Nagoya University, Japan
- TP-16 Secretion of Different Altered Laminin Isoforms Results in Three-dimensional Morphological Changes in Cells Cultured on Matrigel

 Misako Imai, Takeomi Mizutani, Kazushige Kawabata and Hisashi Haga,

 Hokkaido University, Japan
- TP-17 Efficient Generation of Mature Hepatocyte-like Cells from Human iPSCs Hinatsu Ohgane, Takanori Takebe, Keisuke Sekine and Hideki Taniguchi, Yokohama City University, Japan
- TP-18 On-chip Fabrication of Bio-degradable Microstructures for 3D Cell Assembly Ryota Sakakibara, Masaru Takeuchi, Akihiko Ichikawa, Kenichi Ohara, Masahiro Nakajima, Yasuhisa Hasegawa and Toshio Fukuda, Meijo University, Japan

TP-19 Fabrication of Three Dimensional Hollow or Suspended Microstructures Louis Wy Liu, New Education For Life, Hong Kong

TP-20 Electrodeposition of Alginate Hydrogel for Spatially Selective Entrapment of Biological Cells

Zeyang Liu, Masaru Takeuchi, Masahiro Nakajima, Toshio Fukuda,

Yasuhisa Hasegawa and Qiang Huang, Nagoya University, Japan

TP-21 Bubble-based Assembly of Micro-tube with Coordinated Multiple Manipulators
Ning Yu, Xiaoming Liu, Huaping Wang, Shaoqi Chen, Qing Shi, Qiang Huang and
Toshio Fukuda, Beijing Institute of Technology, China

14:25-14:30 *Coffee Break*

Plenary Talk Conference Room 1

Chairperson: Makoto Kaneko, Osaka University

14:30-15:10 Plenary Talk 4

Mechanical Basis of Cell Motility Control in the Developing Brain

Prof. Mineko Kengaku, Kyoto University, Japan

15:10-15:20 *Coffee Break*

Session Session TP1-1: (Organized Session): Bio-Assembler -3

Chairperson:	Nobuyuki Tanaka, Osaka University Yutaka Ikeda, University of Tsukuba
15:20-15:35	High-throughput Cell-patterning with a Self-assembled Bubble-raft Nobuyuki Tanaka, Yuji Haraguchi, Tatsuya Shimizu, Masayuki Yamato, Teruo Okano and Jun Miyake, Osaka University, Japan
15:35-15:50	Quantitative Rheological Measurements of Confluent Cell using Atomic Force Microscopy Ryosuke Takahashi, Kaori Kuribayashi-Shigetomi, Agus Subagyo, Kazuhisa Sueoka and Takaharu Okajima, Hokkaido University, Japan
15:50-16:05	Atomic Force Microscopy for Mapping Mechanical Property of the Whole Cell Assembly Ryosuke Tanaka, Yuki Fujii, Junpei Kikkawa, Kaori Kuribayashi-Shigetomi, Agus Subagyo, Kazuhisa Sueoka and Takaharu Okajima, Hokkaido University, Japan
16:05-16:20	Narrowing Slit Device for High Yield One-to-one Electrofusion and Culture of Fusants without Gene Mixing S. Sakamoto, K. O. Okeyo, O. Kurosawa, H. Oana, H. Kotera and M. Washizu, The University of Tokyo, Japan
16:20-16:35	Cell Pinball Ryo Murakami, Makoto Kaneko, Shinya Sakuma and Fumihito Arai, Osaka University, Japan
16:35-16:50	Impact of ROS Scavenging Effect on Cell Culture and Bio Assembler Yutaka Ikeda, Tomoki Yoshinari and Yukio Nagasaki, University of Tsukuba, Japan

Session TP2-1:(Organized Session): Human Assistive Technologies

	Conference Room 2	
Chairperson:	Yasuhisa Hasegawa, Nagoya University	
	Yoshihiro Tanaka, Nagoya Institute of Technology	
15:20-15:35	Gait Control of Powered Exoskeleton with Finger-mounted Walk Controller for Paraplegic Patient	
	Yasuhisa Hasegawa and Keisuke Nakayama, Nagoya University, Japan	
15:35-15:50	A Wheelchair Operation with an Exoskeletal Robot using User's Residual Function	
	Toshihito Yabunaka, Keishi Yonezawa, Norihiko Kato, Ken'ichi Yano, Yasuyuki Kobayashi, Takaaki Aoki and Yutaka Nishimoto, Mie University, Japan	
15:50-16:05	Wearable Assistive Device for Lower Limbs of Caregiver on Transferring Support	
	Yasuhisa Hasegawa and Takashi Hoshino, Nagoya University, Japan	
16:05-16:20	A Study on Tactile Display for Haptic Sensing System with Sensory Feedback for Laparoscopic Surgery	
	Yoshihiro Tanaka, Shuji Aragaki, Tomohiro Fukuda, Michitaka Fujiwara, and Akihito Sano, Nagoya Institute of Technology, Japan	
16:20-16:35	Force Range Extension and High Force Accuracy with Pinching Support Device by Presenting Haptic Sense Based on Fingertip Sensitivity Yasuhisa Hasegawa and Junichi Muto, Nagoya University, Japan	
16:50-17:00	Coffee Break	

Session TP1-2: (Organized Session): Bio Assembler -4

Chairperson:	Masaru Kojima, Osaka University		
	Kazuto Kamiyama, Osaka University		
17:00-17:15	Temporal Change in Complex Shear Modulus of Cells: An Atomic Force Microscopy Study PingGen Cai, Ryosuke Takahashi, Kaori Kuribayashi-Shigetomi, Agus Subagyo, Kazuhisa Sueoka and Takaharu Okajima, Hokkaido University, Japan		
17:15-17:30	Cell Pairing on a Microwell Array Electrode by Positive Dielectrophoresis Tomoyuki Yasukawa, Yuki Yoshimura, Fumio Mizutani, University of Hyogo, Japan		
17:30-17:45	Asymmetric Lattice-shaped Microchannel Structures for Continuous Size-dependent Cell Sorting Wataru Seko, Masumi Yamada and Minoru Seki, Chiba University, Japan		
17:45-18:00	miRNA-720 Regulates the Stem Cell Phenotype and Differentiation of Human Dental Pulp-derived Mesenchymal Stromal Cells Emilio Satoshi Hara, Mitsuaki Ono, Takanori Eguchi, Hai Thanh Pham, Shoji Tajima, Stuart K. Calderwood, Takuya Matsumoto and Takuo Kuboki, Okayama University, Japan		

Session TP2-2:Robotics and Mechatronics-2

Chairperson:	Yasuhisa Hasegawa, Nagoya University	
	Kenichi Ohara, Meijo University	
17:00-17:15	Development of Wrist Support Mechanism for Muscle Weakness F Work on Desk Work	
	Yasuhisa Hasegawa, Satoshi Shimada an Nagoya University, Japan	nd Kiyoshi Eguchi,
17:15-17:30	Thin Active Fixture to Hold Finger for Excepted Exoskeleton	asy Attachment and Comfort of
	Yasuhisa Hasegawa and Takeshi Suzuki,	Nagoya University, Japan
17:30-17:45	:45 Development of Face Recognition Algorithm for Enhancement of S Communication of Robotic Assistive Autism Therapy	
	Mohd Ridzuan Abdul Samat, Syamimi Sh Hanafiah Yussof, University of Paris, Fra	v
17:45-18:00	Intention-shared User-interface by the Au "See What I See"	nto-discrimination of Gaze Object
	Amalia Istiqlali Adiba, Nobuyuki Tanaka Osaka University, Japan	and Jun Miyake,
18:10-20:30	Reception Party	Universal Club
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November 12 (Wed) Location: Noyori Conference Hall

Session WA1-1: (Organized Session): Young Researchers in Micro-Nano Systems Conference Room 1

Chairperson:	Hisataka Maruyama, Nagoya University Moeto Nagai, Toyohashi University of Technology
09:00-09:15	Direct Assembly of Movable Parts in a Microchannel using a Water-Soluble Sacrificial Layer for Biohybrid Systems Moeto Nagai, Kohei Tanizaki, Takahiro Kawashima and Takayuki Shibata, Toyohashi University of Technology, Japan
09:15-09:30	Trehalose Biofuel Cells using Insect Hemolymph for Insect Robots Kan Shoji, Yoshitake Akiyama, Masato Suzuki, Toshifumi Asano, Nobuhumi Nakamura, Hiroyuki Ohno and Keisuke Morishima, Osaka University, Japan
09:30-09:45	Evaluation of Cell-cell or Cell-substrate Adhesion Effect on Cellular Differentiation using a Microwell Array having Convertible Culture Surface Yuta Nakashima, Kohichi Tsusu, Yuki Hikichi, Tairo Yokokura, Kazuyuki Minami and Yoshitaka Nakanishi, Kumamoto University, Japan
09:45-10:00	Photosynthesizing Cyanobacteria inside Confined Space at Microscale Tadashi Ishida, Ryo Abe, Toru Omata, Nobuyuki Takatani and Tatsuo Omata, Tokyo Institute of Techonology, Japan
10:00-10:15	Non-contact 3D Rotation and Capture Method for Bio-object based on Microfluidic Stream Yaxaier Yalikun, Asano Toshifumi, Yasunari Kanda and Keisuke Morishima, Osaka University, Japan

Session WA2-1: (Organized Session) Micro-Nano Robotics and Mechatronics Conference Room 2

Chairperson:	Akihiko Ichikawa, Meijo University Nobuyuki Futai, Shibaura Institute of Tecgnology
09:00-09:15	A Microfluidic Static Gradient Generator using Limited Diffusuon Through T-shaped Narrow Channels Makoto Tamura, Shugo Maeda, Tomohisa Ogawa, Masato Tanaka and Nobuyuki Futai, Shibaura Institute of Technology, Japan
09:15-09:30	Leakage-free Reconfigurable Microchannel Having Moving Sidewalls Sealed with Hydrocarbon Sealant and Oil Seals Masahiro Oono, Kousuke Mikami and Nobuyuki Futai, Shibaura Institute of Technology, Japan
09:30-09:45	Measurement of Cellular Reactive Force on a Microfluidic Chip using Moiré Fringe Hirotaka Sugiura, Shinya Sakuma, Makoto Kaneko and Fumihito Arai, Nagoya University, Japan
09:45-10:00	Estimation Method of Operating Force using an Extended Kalman Filter Based on Ground Reaction Force and Human Behavior Taishi Noro, Yusuke Katsuda, Takanori Miyoshi and Kazuhiko Terashima Toyohashi University of Technology, Japan
10:00-10:15	The Study of Medical Micro Device for the Next Generation Brain Intravascular Treatment Akihiko Ichikawa, Takahiro Itou, Kouhei Shimogaito, Takashi Kubo and Toshio Fukuda, Meijo University, Japan
10:15-10:30	Coffee Break

Keynote Talk		Conference Room 1
Chairperson:	Takaharu Okajima, Hokkaido University	
10:30-11:00	Keynote Talk 1 Microbial Rhodopsins from Marine Bacteria: Light-driven Ion Pumps Assistant Prof. Keiichi Inoue, Nagoya Institute of Tech	
11 :00-11 :30	Keynote Talk 2 Active Biophysical Properties of Cells and Subcellular Components Associate Prof. Shinji Deguchi, Nagoya Institute of Technology, Japan	
11:30-11:40	Coffee Break	
11:40-12:00	Award Ceremony	Conference Room 1
12:00-13:30	Lunch	
13:30-15:00	Laboratory Tour	Nagoya University